

Hi-Tech CNC Systems



OPEN*control* Product Overview

Roberto Roagna Product Marketing Manager

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Hi-tech Numerical Control family OPEN*control* Osai Prima Electro Numerical *control*





Index

OPEN*control* system architecture
OPEN*control* CNC models
OPEN*control* software
Operator Panels and Handheld Terminals
Servodrives & Motors
I/O modules

Hi-Tech Numerical Controls & Peripherlas



OPENcontrol

- high scalability • hardware configurations computational power software performances
- suitable for several applications •

MARKETS:







STONE

GLASS & ALUMINUM & SHEET METAL



ADDITIVE





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OPEN*control* SYSTEM ARCHITECTURE

Single hardware module

Real Time and HMI running on the same HW

One fieldbus for drives and I/Os

Optional secondary fieldbuses for I/Os and devices

Single Operating System Real Time SW and HMI on WEC7 or Dual Operating System Real Time SW on WEC7 HMI on Windows 10 IOT. Real Time and HMI connected through virtual network



Single module configuration



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OPEN*control* SYSTEM ARCHITECTURE

Two networked hardware modules

Real Time on CNC module, HMI on PC

One fieldbus for drives and I/Os

Optional secondary fieldbuses for I/Os and devices

Dual module configuration



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OPEN*control* CNC models





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Four CNC models available: OPEN*smart*, OPEN*key*, OPEN*prime* and OPEN*prime-i*

Model choice is determined by the required perfomances in terms of block cycle time, minimum system tick, number of Processes and Axes, number of fieldbuses and devices used by specific configurations





OPEN*prime* OPEN*prime-i*

OPEN*key*

OPEN*smart*





* Computational power, Flexibility, Fieldbus range, Features



CNC Technical data overview

	OPEN <i>s</i>	OPEN <i>key</i>			OPEN <i>prime/prime-i</i>			
CNC								
Interpolator Tick	2 m	IS	1ms			500µs		
Max interpolated axes	8			16			64	
Max axes number	16 (*)	24 (**)			64 (***)		
Processes	2			4			24	
Retentive memory				Har	dware			
OPERATING SYSTEM								
Dual O.S.	Available							
PERIPHERALS								
LAN	1		up to 2		2			
RS232			1					
RS232/422/485	1							
USB		1 x 3.0*			2 x 3.0 2 x 2 0			
Video			DVI-I				DVI-D + VG	4
FIELDBUS								
Fieldbus 1	EtherCAT	ML III	EtherCAT	ML III	ML II	EtherCAT	ML III	ML II
Fieldbus 2	CAN	EtherCAT	CAN	EtherCAT	EtherCAT	CAN	EtherCAT	EtherCAT
Fieldbus 3	-	-	-	CAN	CAN/Profibus	-	CAN	CAN/Profibus
INTEGRATED I/Os								
Power ON enabling Out				```	YES			
Fast I/O	1 lr	า			3 Ou	it, 4 In		
Analog In 1	-				12 bit res./ \pm	10V o 4÷20 m	۱A	
Analog In 2	-				12 bit re	es./ \pm 10V		
Analog Out	-				1 x 16	bit res.		
Encoder In	-				1 x A	BZ Inc.		
21	(*) of w	hich max		(**) of whic	h max olink		(***) of whi	ch max 10



8 Mechatrolink

12 Mechatrolink

62 Mechatrolink

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OPEN control software





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OPENcontrol 100% customizable



Machine Logic

HMI

ISO programming

Communication library

Integrated SoftPLC

arra (*	(1) and Bellfreemen	

CNC	THC505_1	- 00000	MESSAGGID 2 DE	LOGICA SYSTEM HIS	STORY
HODE	HANDOG	×	0.00000	0.00000	0
UNIT	TIDLE TIDLE	Y	0.00000	0.00000	0
	-	z	0.00000	0.00000	0
	THE R.		0.00000	0.00000	0
0.00	a faiture	20(2000)		0.00000	0

WinNBI

Programming

- O X

//Was/admin/Projects/Editor/1.0a/1234.nc	
%	
01234 (THIS IS A COMMENT)	
G0 G40 G97 G99 X150, Z150, S170 M4	
NO (DO SOMETHING)	
T200 M16	
G0 X56.5 Z4, T202 M8	
G96 S25	
G1 G41 X51.5 Z1. F0.05	
×49.55 Z0.	
×49.35 Z-0.1	
×49.25 Z-2. F0.1	
G0 G40 X45. Z5.	
TO	

Communication library





WinPLUS Integrated SoftPLC



- Development environment based on IEC 61131-3
- IL, LD, ST, FB, SFC programming languages
- Integrated machine logic environment
- Multi-tasking real-time execution
- Max 250 tasks, 10 priority levels
- Cyclic task with min. scheduling of 250 µSec.
- User event-driven tasks
- Event tasks associated to M, S, T functions
- On-line debugging (tracing, breakpoint etc.)

- Programming environment for full system customization
- Powerful development environment
- More than 350 functions available
 - HMI data exchange
 - ISO program data exchange and synchronization
 - Axes motion and interpolation •
 - File access

•

MH00

- Media and fieldbus access •
- Data Table access ٠
- Part Program management •
- Drive parameters access
- Several base functions

Standard Functions

SETMODE

C++ functions integration

- Synchronization with the system
- System library access





HMI customization

			Int Int Int Int Programmed 0000 100 0000 000 00000 0000 0000 0		ProcessCo	ntroller/Layout[Builder
	24	≓ i 90000.090	SAI ProcessControlle	r - [new-osai_p6a]			- • ×
			File Display Select S	et Up Origin/Tool Part Pro	ogram Utility ?		
				〕153 ₩ ₩ ₩ ₩ FBO	♥■ \+ <u>-</u> +		
			CNC IP.192.168.157.2	▼ ▼ ▼	· · · · ·	-	
			Mdi Au	uto 🏶 Bik-Bik 🏶 Pr	ofile 🏶 Jog 🌵	Jog Inc 🔅 Ref 🔅	HandW
Several standard user screen panels su	polied with CN	IC	MANJOG IDL	E mm PARTP	.txt		
software			CNC IP.192.168.1	57.2 Proc 01	Work	Programmed	Origin
Soleware	-				Y 0.000	00 0.00000	0
Easy screen panels customization base	d on automatic	С			Z 0.000	0.00000	0
graphical objects					A 0.000	00 0.00000	0
5. aprilate objecto			Tool		B 0.000	00 0.00000	0
No software required for automatic ob	ojects		Next T Diam O.O	000			
Data averbando with DLC for custom of	ioct		Offs 1 0.0	0000 Attic 1	Programm Feed Rate 0.1	ed Percent	Actual
Data exchange with FLC for custom of	iject		O Strop Dry R Retr Mem 1	S Artn 1 Ran 0 Blk Del E Bun	Feed Man 0.0	JOO - 100.0 % +	0.000
management					Rapid 0.1	00 - 100.0 % +	0.000
			Jog 🗠 🕂 0.1	000			
			N10GXYZ100 N20X10Y10				
			N30G1Z5F1000 N35G1X10				
			N40X100Y150				



Key features

Axes Management

- Coordinated, Auxiliary, Pseudo and Spindle axes
- Linear and Rotary Axes
- Rollover Axes
- Diameter Axes
- Gantry Axes (Split)
- Dual Axes (UDA, SDA)
- Master/Slave axes (XDA)
- Dynamic follower axes (AXF)
- Gantry Axes (Split)



Axes Motion

- Linear, Circular, Circular 3D, Helical, Helical 3D and Spline Interpolation
- Rounding Corners
- Axes Reference System
- Tool radius Compensation
- Motion Modality (accel and decal RAMP parameters)
- Linear Ramp
- S Ramp
- Trapezoidal Ramp
- S Ramp with Jerk limitation
- Point to Point and Continuous Modewith Lock Ahead
- Axis motion filters (FLT)
- Velocity and Acceleration Feed Forward (VFF and AFF)
- Tangential Axis Control (AXT)
- Constant or Variable Pitch, Multi-start Threading (G33)

Motion Features

- Axis Migration and Sharing
- Zero Shift
- Multi Block Retrace
- Memory Block Search (Program restart)
- Active Reset
- Protected Areas
- Working Cycles for Turning Systems
- Part Program Execution Time Estimation

Special Features

- Multi-Axis Electronic Cam
- Bidirectional axis calibration
- Volumetric and Cross Compensation, Axis Calibration





Key features

3D Axes Motion

- Circular 3D interpolation
- Tangential axis control
- Tool Centre Point (TCP)
 - TCP for Machine with Double Twist and Prismatic Heads
 - TCP for non-standard kinematics
 - TCP with tool direction axis and relevant rotated plane
 - TCP with Spline (High Speed Machine)
 - Tool Direction axis movement
 - TCP on rotated planes
 - Selection by program of active kinematics





Virtualization

- Programming on Rotated Plane
- Polar Coordinates
- Cylindrical Coordinates
- Non-orthogonal axes management



Various

- Unit of measure change
- Shared Axes
- Axis Migration
- Parametric (macro) language
- Machining canned cycles
- Probing cycles
- Part-program subroutines
- XML macro interpreter

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WinNBI Windows Network Based Interface

End-user tools. Programming and machine operations





* Not available for single platform single O.S. configuration

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WinNBI Windows Network Based Interface

OEM tools. Machine Setup and Diagnostic



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* Not available for single platform single O.S. configuration

OFFLINE CNC SIMULATOR (DIGITAL TWIN MACHINE)



Windows 10, Dual O.S. layer, Windows CE (WEC7), CNC software running on a standard PC

- Development, running and debug of PLC programs
- Writing and testing of part programs
- Development and debug of software communicating with the CNC
- Same behavior as for CNC, same software used on both environments
- Same HMI used for the "real" CNC.
- Updates with the same software and same procedures used for the "real" CNC
- Absence of connection with devices (servo-drives and I/Os), if needed, can be simulated via the PLC.



Communication Library





TCP/IP

i4.0 on-board Servers

In order to guarantee the connection to external systems OPEN*control* onboard Servers implement standard and vendor-independent Industry 4.0 protocols such as:

OPC UA (Open Platform Communications - Unifed Architecture) MQTT (Message Queue Telemetry Transport) protocols

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1 4 2 24	47.					<%>			11 11 201		Labora danad	
	ID	Туре	Description				Date	Time	Code	Process	Source line	Source file
7	1829	Anomaly	Access Violation Exception	n			13/07/2018	11:25:04:244	3866634			
2	1827	Anomaly	Division by 0				13/07/2018	11:2641:771	3886634			
0	1832	Error	Command and system star	tus not congruent Status ERROR (D	UMMY) Command SELECT PROGRA	un .	13/07/2018	013151889	1441954	1		
3	1831	Log	Message from PLC : Work	session 2 - Part C - 152156			13/07/2018	01:33:21:16				
	1826	Log	Message from PLC : Work	session 3 - Part D - 152157			13/07/2018	01:35:37.225				
3	1833	Log	Message from PLC : Work	session 3 - Part D - 152158			13/07/2018	01-36:58:670				
	1838	Emergency	ShutDown				29/08/2018	07)48:52:705	90 255	0		
	Program		Op, Mode	Error *	Emergency	Error .	Anomaly		Op. Mode	1	Program	Error
07/21	Aessage: Fart A ata/Time: 118 08:17:1 Process: 1	9297	Message: Manyal Date/Time: 12/07/0018 13:46:30:906 Process: None	Description: Pother Limit reached during movement on axis 2 (id 3) Position 33.00000 Limit 33.00000 Limit 23.00000 Limit <td>Messapic OS-Wire Communication entro Node 8 Data/Time: 12/07/2018 2355325543 Preces: 0</td> <td>Description: Command and system status not computer Status ERROR (DUMMIN) Command SELECT PROCEAM Date/Time: 13/07/2018 01315/08/9 Process: 1</td> <td>Description: Access Violation Esception Tude/Time: Tude/Time: Tude/Time: Tude/Time: Tude/Time: None</td> <td>22,07/</td> <td>Description: Automatic Date/Time: 2018 22:28:22:80 Process None</td> <td>4 23/07</td> <td>Description: Part C Date/Time: /2018 12:18:27:407 Process: 1</td> <td>Descriptio NCUSER error Date:/Tim 23/07/2018 14/28 Process: 1</td>	Messapic OS-Wire Communication entro Node 8 Data/Time: 12/07/2018 2355325543 Preces: 0	Description: Command and system status not computer Status ERROR (DUMMIN) Command SELECT PROCEAM Date/Time: 13/07/2018 01315/08/9 Process: 1	Description: Access Violation Esception Tude/Time: Tude/Time: Tude/Time: Tude/Time: Tude/Time: None	22,07/	Description: Automatic Date/Time: 2018 22:28:22:80 Process None	4 23/07	Description: Part C Date/Time: /2018 12:18:27:407 Process: 1	Descriptio NCUSER error Date:/Tim 23/07/2018 14/28 Process: 1



In addition, OPEN*control* includes a data-base containing a wide quantity of information and data (same that can be transmitted run-time via OPC UA and MQTT) permanently stored and historicized.

Historicized data are available for external diagnostic applications connected to the NC via SOAP protocol and can be displayed on the control in the system journal (System History) application for machine maintenance.



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OPERATOR PANELS & HANDHELD TERMINALS

Each OPEN*control* CNC model can be combined with different operator interfaces, from the simple Touch Screen monitor, to OPEN*console*, the High End modular Operator Panel.





COMPACT console TS2

Ergonomic Operator Panel including all commands required to manage machines tools Thanks to the high configuration flexibility it can easily suit any type of application

- 15" Touch Screen Monitor (1024 x 768)
- Customizable Control Panel (standard functions: operation mode selection, Cycle Start, Hold, Reset plus 3 buttons for general functions)
- 2 customizable rotary selectors (standard functions: spindle and cutting speed override)
- Emergency button set-up
- Set-up for 2 electromechanical elements (buttons, selectors etc.)
- 1 USB port







COMPACT*console* TS2

OPERATOR PANEL				
Control panel				
Emergency Stop	Optional			
Set-up for electromechanical buttons	2 with 22 mm Ø hole for standard buttons			
Cycle Start	YES (customizable)			
Cycle Stop (Hold)	YES (customizable)			
Reset	YES (customizable)			
Operation mode selection keys	MDI, Automatic, Block by block, Jog, Jog Incremental, Homing, Return on			
operation mode selection keys	profile, Handwheel (customizable)			
Rotary selectors	Feed rate Override (customizable)			
	Spindle speed Override(customizable)			
Customizable OEM keys	3			
USB connection	1 with protection cap			
Connection	EtherCAT			
Monitor				
Dimensions / Display	15" - 4:3			
Resolution (pixels)	1024 x 768			
Connection	VGA / DVI			
Touch Screen	Resistive			

KEYBOARD				
Layout	USA			
N° of keys	87			
Pointer	Touch-pad			



OPEN*console*

OPEN*console* has been designed to meet many different application requirements.

Its modules can be combined in order to create a customized interface suitable for several machining types and for numerical control machines.

Modular HMI system

- 17" 19" Touch Screen Industrial Monitor (1280 x 1024)
- Main MTB Panel
- MTB Panel extension (customizable)
- Keyboard with touch-pad or track-ball





OPEN*console*

Monitor

- Monitor 17" or 19" Touch Screen
- VGA and DVI connection 4:3 format

MTB panel

- EtherCAT fieldbus
- Emergency push-button
- CNC specific push buttons
- Feed override knob (configurable)

MTB panel expansion

Customizable 7 elements (keys, push-buttons, lamps etc.)

Keyboard

- 101 keys US keyboard
 Touch Pad or Track Ball
- USB port

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OPERATOR PANEL			
Monitor			
Size	17" o 19"		
Resolution (pixels)	1280 x 1024		
Connection	VGA / DVI		
Display ratio	4/3		
Touch Screen	Resistive		
Control panel			
Emergency Stop	YES		
Drives ON/OFF	YES		
CNC power ON/OFF	YES		
Cycle start	YES		
Cycle Stop (Hold)	YES		
Reset	YES		
JOG + / JOG -	YES		
Mode selector	Automatic, Manual		
Mode Lock key	YES		
Override controls	Feed Rate (customizable)		
OEM Custom keys	On additional module		
Connections	EtherCAT		
KEYBOARI)		
Layout	US 101 Keys		
Pointing device	Touch-pad / Track-ball		
Power Supply	USB		
Туре	Silicon keyboard		
Operating Temperature	0°C to +50°C		
Humidity	10% to 90% no condensation		

Industrial Monitors

Complete line of industrial monitors for panel mounting

Resistive touch screen Different types of input ports Solid and light metal frame.

All models are supplied with a 24VDC and include an adapter for 220VAC power supply

A remote controller for front calibration allows modifying settings without opening the electrical cabinet.

With a format ranging from 10.4" (resolution 800x600) up to 17" (resolution 1280x1024), these monitors suit a wide range of applications being the perfect complement of OSAI CNC models for CNC or General Motion Control applications.





Industrial Monitors

	10,4″	15″	17″			
Active Display Area (mm)	211 (W) x 158 (H)	304 (W) x 228 (H)	338 (W) x 270 (H)			
Display ratio						
Resolution	800 x 600	1024 x 768	1280 x 1024			
Brightness (cd/m ²)	250	350	250			
Contrast Ratio	500:1	700:1	1000:1			
Viewing Angle	140(H) / 110(V)	140(H) / 125(V)	170(H) / 160(V)			
Response Time	5ms	4ms	5ms			
Backlight	LEI	CCFL				
Power Consumption	≤ 25W(≤ 35W(Max)				
Touch Screen Type	Resistive (5wires)					
	Auto adjust, Brightness, Contrast, Hori./Vert. Position,					
OSD Controls	Colour, Language					
	Remote controller for calibration purpose included					
Input Ports		HDMI, DVI, VG	A			
Dowor Supply		12V - 24V dc ±	5%			
Power suppry	220	VAC - 12V dc adapte	er included			



OPEN*wiTP*

Light, easy to manage, with an ergonomic design, OPEN*wiTP* is a reliable wireless remote control for CNC-machining centers.

Terminal

- High resolution 4.3" TFT display
- Battery for 8h+ operation with full charge (battery charger integrated)
- 3 levels Enabling device pushbutton
- Emergency stop (E-Stop) pushbutton
- Two-hand operation keys
- 2 rotary selectors
- Keyboard with navigation stick
- 5 MP camera with auxiliary white LED
- NFC reader/writer
- Magnetic hooking on the rear, for ease of use in field

Base station

- Compact module for electrical cabinet
- Standard DIN-rail mounted module
- Antenna extension cable supplied





OPEN*wiTP*

CNC pages

Several predefined pages allow the management of the machine tool in AUTOMATIC mode, MANUAL mode (including handwheel mode) and DIGITIZING while a custom page, simply defined through a configuration file, allows to display and edit specific machines data

	UTOMAT	IC	
Proc 1	Currl	Proc 1	G1
Axis	Work	pos	Proc
X 3	9 440		Axis
	0.110		Work po
Y 0	.000		Progr p
Z 0	.000		Progr F
A 0	.000		FRO
B 0	.000		Actual F
FRO <mark>70</mark>	₽ F 0	.000	
SSO <mark>70</mark>	🗄 S 0	.000	PosTyp
RAP 90			
			P. L. O. L
BACK	POS	GMT	BACK

To AUTOMATIC.POS		
G1		
Proc	1	
Axis	×	
Work pos	39.4	40
Progr pos	0	4.8
Progr F	0	H.W.
FRO	70	41
Actual F	0.00	0
PosType	Woi	'k
BACK	1	GMT

CUSTOM		
Titolo del	la pagina custom	
MD50	63.0000	
MD50_RO	63.000	
MW110.i	0	
MW110_RW	0	
MW110.0_RO	0	
MW110.1_RO	0	
MW110.2_RO	0	
MW110.3	0	
MD51	0.000	
MW110.15_R	0	
BACK	1	





OPEN*wiTP*

Standards, regulations and certifications

Applied standards

- EN ISO 13850:2015 (Safety of machinery-Emergency stop function)
- EN 60204-1:2014 (Safety of machinery-Electrical equipment of machines)
- EN ISO 10218-1:2011 (Robots and robotic devices-Safety requirements for industrial robots)

Functional Safety Certification

IEC 61508 - Functional safety of electrical/ electronic/ programmable electronic safetyrelated systems Level - SIL3

- Enabling device button
- Emergency stop button

Display	TFT 4.3" 480x800		
Keyboard	4-direction + center push joystick 3 soft keys 2 rotary selectors On/off key Start key 3 status LEDs		
Wi-Fi	Dual band 802.11a/b/g		
NFC	Contactless communication at 13.56 MHz - read/write ISO/IEC 14443A/B NFC tags type 1-2-3-4 ISO/IEC 15693 - MIFARE		
Camera	5 MP Autofocus Barcode reader Live streaming video for remote diagnostics Auxiliary LED flashlight		
Dimensions mm (inch)	325 (12.8) x 94 (3.7)		
Battery	Li-ion 7.2V 5.8Ah		
Ingress protection	IP54		
HW specification	Dual parallel channel architecture (1002). Either channel can process the safety function.		
Pairing	Secure wireless pairing through black channel with unique IDs		



OPEN*wiHT*

Compact and lightweight device with an ergonomic design

Wireless connection with certification for safety devices

Integrated devices (Keyboard, potentiometers, handwheel) are fully programmable assuring flexible application to any automation project

Terminal

- 5" TFT color display
- 480x272 pixel resolution, 64K colors
- Resistive touchscreen
- 2 USB Host ports (upper, lower)
- Emergency stop button
- 3-positions enabling switch
- 16-positions state selector
- 2 potentiometers
- 1 optional handwheel
- 19 user-programmable selection keys
- NFC reader, accelerometer, buzzer, vibration motor







Receiving Station



Recharging Station

OPEN*wiHT*



System Resources		
Display - Colors	5" TFT LED - 64K	
Resolution	480 x 272	
Brightness	300 Cd/m ² typ.	
Touchscreen	Resistive	
Handwheel	YES	
Potentiometer	2	
Programmable keys	19	
State Selector Switch	16 positions, 24 V_{DC} / 0.5A outputs (high side drivers)	
Emergency stop	YES, 24 V _{DC} / 0.5A outputs (relays)	
Enabling switch	3 positions, 24 V _{DC} / 0.5A outputs (relays)	
Interface		
Ethernet	Wi-Fi 802.11a/b/g	
USB port	2 Host V2.0	
Ratings		
Power supply (charging station)	0.8A max. @24 V _{DC} (10 to 32 V _{DC})	
Input Protection	Reverse voltage, overvoltage	
Battery	Rechargeable Lithium battery, user-replaceable	
Environment Conditions		
Operating Temperature	+5° to +45°C	
Storage Temperature	-20° to +70°C	
Operating / Storage Humidity	5-85% RH, non-condensing	
Protection Class	IP64 (terminal)	
Dimensions & Weight		
Faceplate LxH mm (inch)	220 (8.66) x 144 (5.67)	
Depth D+T mm (inch)	63 (2.48)	
Weight (Kg)	0.8 (approx.)	

bsa

SERVODRIVES & MOTORS

Different solutions - stand-alone, rack, EtherCAT and Mechatrolink III drives perfectly matching OPENcontrols for high dynamics and high precision motion





OD700 SERVODRIVES

- EtherCAT interface
- Compact mechanical dimensions
- Wide range of operating currents and power supply voltages
- Six available sizes, in four different mechanical formats
- Nominal currents of 3A, 4,5A, 6A, 12A, 18A and 36A
- Integrated security function STO (Safe Torque Off)

WinNBI "ODM" (OSAI Device Manger), a powerful integrated browser able to simultaneously manage all connected drives and motors, allows both the visualization and the modification of motors and drives parameters, as well as the diagnostic analysis of the drive through several graphical pages easy to use.

WinNBI "OScope" allows full dynamic monitoring of OD700 behavior displaying the servo-drive values on several traces. Synchronous CNC data and part program blocks execution shown by OScope togheter with axis values traces allows fast and easy diagnostic.





OD700 SERVODRIVES

ODM interface



	OD700 OPEN <i>drive</i>					
Rms current	3A	4,5A	6A	12A	18A	36A
Peak current		9A	12A	24A	36A	108A
Dimensions (h, d, w) [mm]	183 x 200 x 65		275 x 266 x 73 310 x 266 x 104		320 x 310 x 90	
Protection	Overcurre	Overcurrent, overvoltage, over-temperature of the drive. Overcurrent and over-temperature of the motor				he motor
Connection	2 x RJ45 for EtherCAT, 1 x RJ45 for Ethernet, D-sub connectors for main and auxiliary motor feedback Removable power connections					
Power supply		23	0VAC ÷ 480VAC ±10	0% Three-phase		
Integrated Clamp Resistor	60W			100W	200W	NO
External Clamp Resistor	Optional Always					
Local diagnostic		7 segments display				
Safe Torque Off (STO)	YES					
Transducer interface Port 1	Encoder SinCos 16/1024 Hiperface Single/Multi turn, Incremental SinCos 1Vpp, Incremental ABZ + Hall, Resolver, Incremental Sincos 1Vpp+Hall, ABZ, ABZ+Hall Proprietary 20 bit serial absolute					
Transducer interface Port 2	Incremental SinCos 1Vpp, Incremental ABZ					
Digital input	Rapid Halt, Zero switch, Fast Touch Probe (optoisolated, programmable)					
Other digital inputs	1 optoisolated, programmable (i.e. Gantry axes emergency management)					
Digital output	Drive ready					
Other digital output	3 optoisolated, programmable (i.e. Gantry axes emergency management)					
Motor brake	Driven directly by the drive					
Parametrization &	Integrated on CNC, executable on Windows. Parameters setup, diagnostic and monitoring functions through oscilloscope					
Programming	Drive connection through EtherCAT port (CNC) or local browser connected to drive through Ethernet port					
Cooling	Forced cooling					
Operating temperature	-:	20÷55°C	Fro	20- 20 m 45÷55°C with de	÷45°C e-rating (-3% for each	°C)
temperature			Storage: -25	÷70°С		
Humidity	10% ÷ 90% no condensation					



YASKAWA SIGMA-5 SD

- Combined spindle & servo system
- Modular Multiaxes Drive (up to 10 modules)
- From 5.4 to 51 Amp axis modules, 480 VAC
- MECHATROLINK-III high-speed networking
- Overload 350% for 3 5 sec, high peak torque
- STO(Safe Torque Off)
- High resolution absolute encoder
- Advanced and easy to use autotuning
- Power regenerative converter recovers braking energy back to the mains supply

Available on specific driver module with Safety

- STO
- SS1 (Safe Stop 1)
- SS2 (Safe Stop 2)
- SLS (Safe Limited Speed)
- SLS-BP (Safe Limited Speed Based on Position)







I/O MODULES

Wide range of distributed digital and analog I/O peripherals including Analog and P&D servodrive management modules









BRIDGE MODULES

EtherCAT slave modules for managing several I/Os and Analog or Pulse&Direction axes

Optimized for machines with 3 or 5 axes in Gantry configuration

Can be used with all the OPENcontrol CNC models

Four models available to manage:

- 4 or 6 Analog axes, Spindle, Handwheel, Analog and Digital I/Os
- 4 or 6 P&D, Spindle, Handwheel, Analog and Digital I/Os





BRIDGE MODULES

	A-432 4 Analog axis module	P-432 4 P&D axis module	A-664 6 Analog axis module	P-664 6 P&D axis module	
P/N	2SMPM5991/0C	2SMPM6214/0C	2SMPM5992/0C	2SMPM6215/0C	
Axes number and type	4 Analog ±10%	4 Pulse&Direction	6 Analog±10%	6 Pulse&Direction	
Transducer	Incremental encoder				
Digital Input	32		64		
Digital Input filter		1 pole, t = 4.7ms			
Digital Output	32 64				
Digital Output on 24V	24Vdc 0.25A channel (4A max for each connector grouping 8 output)				
Analog Output	2 x 16 bit	-	-	-	
Analog Input	4 x 12	bit			
Spindle Output	1 x analog 16 bit				
Handwheel Input	1 x encoder ABZ				
Power Supply	24 V _{DC}				
Power Supply Digital I/O board	24 V _{DC}				
Operating temperature	0°C +50°C				
Relative humidity	90% no condensation				
IP Protection	IP20				



OPEN*rio SL*

OPEN*rio SL* is a distribuited, modular I/O system with EtherCAT interface designed and produced for:

- communication and process control
- general control and automation applications
- industrial applications

The system is made by the following components:

- EtherCAT Bus coupler
- Periphery modules like digital and analog I/O
- Relay output module
- PWM output module
- Encoder input module

The bus coupler interface and power module are integrated in one casing





bsai

OPEN*rio SL*



	OPEN <i>rio</i> SL				
Fieldbus (Bus Coupler)	EtherCAT				
Assembling	DIN rail mounting - modules connected with side contacts				
Dimensions (W x H x D)		15 x 109	x 76,5 mm		
I/O signals isolation		Electrical	ly isolated		
Digital modules	8SMPM02	1-1BF00	8SMPM02	2-1BF00	
Number of I/O	8 Inj	put	8 Output		
Current for each output	-		0,5A (max 4 A per module)		
Low level input signal	0÷5 \	VDC	-		
High level input signal	15÷28,	8 VDC	_		
Power modules	8SMPM02	2-1BD20	8SMPM02	2-1HB10	
Number of I/O	4 Out	tput	4 Relay	Output	
Current for each output	2A (max 4A per module)		3A 30 VDC / 230 VAC		
Analog modules	8SMPM031-1BB40	8SMPM031-1BB70	8SMPM031-1BD70	8SMPM032-1BB70	
Number of I/O	2 Input	2 Input	4 Input	2 Output	
Input/Output field	0/420mA	±10VDC	±10VDC	±10VDC	
Resolution	12 bit				
PWM Module	85MPM022-1BB90				
Number of I/O	2 Output				
Current for each output	0,5A				
Switching frequency	Max. 40 kHz				
Encoder Input Module	85MPM050-1BA10				
Input voltage for signal "0"	Differential RS422 signal				
Input voltage for signal "1"	Differential RS422 signal				
Maximum input frequency	500 kHz				
Input resistance	120 Ω				

OPENrio V200

Distribuited, modular I/O system with CANopen interface

Modules

- CANopen BUS coupler
- 8 Digital Input
- 16 Digital Input
- 8 Digital Output
- 16 Digital Output
- 8 configurable Digital Input or Output
- 4 Relay out
- 2 + 2 Analog Input Output (configurable +/- 10V or 0 ...20mA)
- 4 Analog Input (+/- 10V)

All the modules		
Dimensions (W x H x D)	25.4 x 76 x 88 mm	
Operating temperature	0°C +60°C	
Relative humidity	5% to 95 % no condensation	









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